



# DETECTLINE

## Fire Engine Version

### Installation, Maintenance & Test

#### AN OPERATIONAL AID

Detection of powered overhead lines  
from 20000Volts~.

For low voltage electric lines (380V) the system does not function.  
The system does not function for Direct Current lines.

**Attention :** The operator must use maximum VIGILANCE and ATTENTION when near powered electric lines.



**M A D E**

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## 1 DOCUMENT OBJECTIVE

This document is the guide to installation and use of the Fire Engine version of DETECTLINE.

Within it are given the details specific to the Fire Engine version,

In particular, those concerning the installation, maintenance and testing of the system.

- Wiring diagrams,
- Component Nomenclature,
- Replacement parts nomenclature,
- A maintenance & repair manual for all electrical parts, within the framework of technical training for personnel to perform first level maintenance,

For the user, the specific file « FS\_detectline\_pompier\_V\_1\_02\_SDIS\_\_.pdf » is more appropriate

## 1 SAFETY INFORMATION

### 1.1 Safety recommendations:

Please read this manual carefully before unpacking, configuring or using this equipment. Note all indications of danger and other warnings. The failure to observe these recommendations could result in serious injury to the operator or could damage the equipment. To ensure that the protection provided by this equipment is appropriate, do not use or install it other than in accordance with the conditions indicated in this manual.

Dismantling the cases is forbidden. This operation is limited exclusively to personnel qualified by MADE.

### 1.2 Following the safety recommendations:

**DANGER** : Indicates a dangerous or potentially dangerous situation which, if not avoided, could cause serious or deadly

**NOTE** : potentially situation cause moderate



Symbol requiring reference to the instruction manual for instructions concerning operation or safety recommendations

Indicates a dangerous which could superficial to injuries.

**Remark** :  
that merits

Information mention.

### 1.3 Warning Labels

Read all labels and wordings shown on the instrument. Bodily injury or equipment damage could occur if these instructions are not respected.

	Dangerous Voltage
	AC current
<b>IP 22</b>	IP standard – Protection against dust and water : TRANSMITTER
<b>IP 65</b>	IP standard – Protection against dust and water : RECEIVER

## 2 TERMINOLOGY

The Fire Engine version of DETECTLINE is an adaptation of the DETECTLINE product.



## 2 OVERVIEW

The Fire Engine version of DETECTLINE equips long-ladder vehicles, fitted with a ladder having combined or automatic movement from 20 meters to more than 52 meters depending on the model.

MADE SA proposes a simple and quick-to-use system in view of the urgent nature of fire interventions.

The adaptation of DETECTLINE to this environment takes into account in particular the constraints associated with the ladder : this is laid on the roof of the vehicle and overhangs by about 80 cm, which constitutes a large metallic mass in the middle of the carriers roof.

The chosen solution consists of equipping the DETECTLINE with a second sensor so that there is a sensor either side of the ladder so as to optimise the zone of coverage of the detector and avoid any perturbations which may be caused by the ladder.

Another constraint taken into account is to not exceed 3.3m overall height.

The Control Module is placed in the cabin and a remote control box in front of the equipment operator's seat is used to operate the system. The system turns on automatically in silent mode at vehicle start-up.

By means of the ON-OFF button, on arriving at the intervention site, the equipment operator can activate the audible alarm. A safety start-up system can also be coupled to the power take-off control (or the hand brake lever).

The presence of the Control Module or the remote control box close to the equipment operator's seat enables him to be aware of the system state before getting down to operate the fire engine equipment.

## 2.1 Dangerous Environments

### DANGER :

Even though some of the systems supplied by MADE are designed and certified for installation in dangerous environments, several MADE systems are not intended for use in such environments. It is incumbent upon those who install these systems in dangerous environments to determine the acceptability of the system for its environment. Additionally, to guarantee safety, the installation of systems in dangerous environments must be compliant to the order specification of the manufacturer. Any modification of systems or their installation is not recommended and could cause deadly injuries and/or damage to facilities.

## 2.2 Reminder

### AN OPERATIONAL AID

#### Detection of powered overhead lines from 20000Volts~.

For low voltage electric lines (380V) the system does not function.  
The system does not function for Direct Current lines.

**Attention :** The operator must use maximum VIGILANCE and ATTENTION when near powered electric lines.

## 3 SYSTEM COMPONENTS

The system COMPRISSES :

- 1 DETECTLINE Central Control Module
- 1 Remote Control and Display box
- 2 DETECTLINE sensors
- 2 extension cables (Lumberg connector) of 10m each
- 1 interconnection cable between the CCM & the Remote box (Lumberg connector)



## 4 INSTALLATION

### 4.1 Installation of the Central Control Module

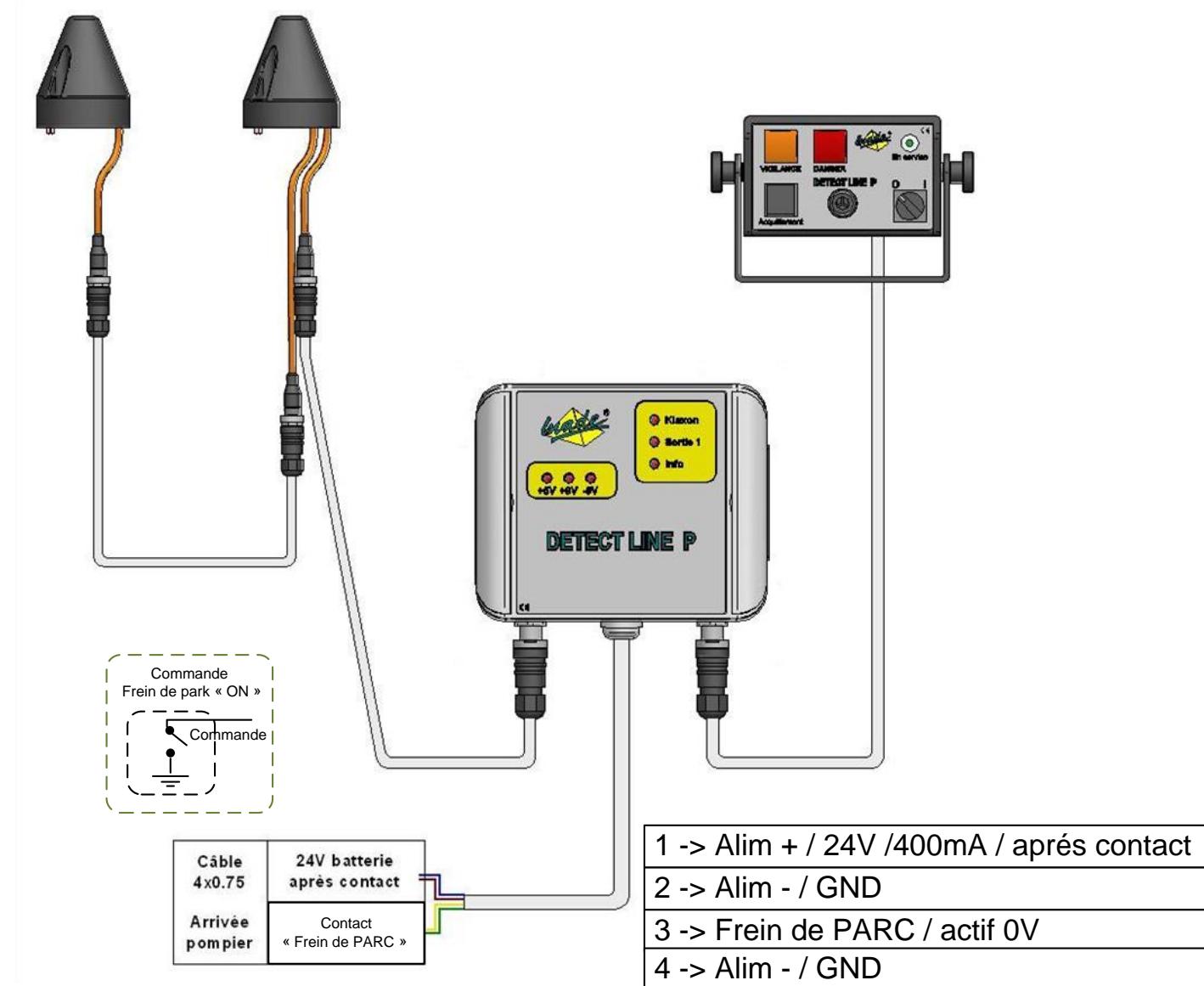
The CCM is installed in the cabin, the remote box is fitted in front of the vehicle equipment operator.

Carry out the following connections (Cf. photo and layout scheme § 5.2.1, parts framed in red) :

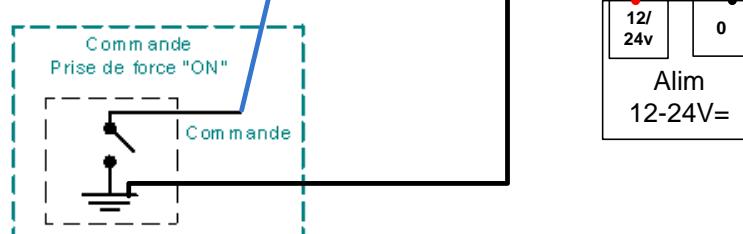
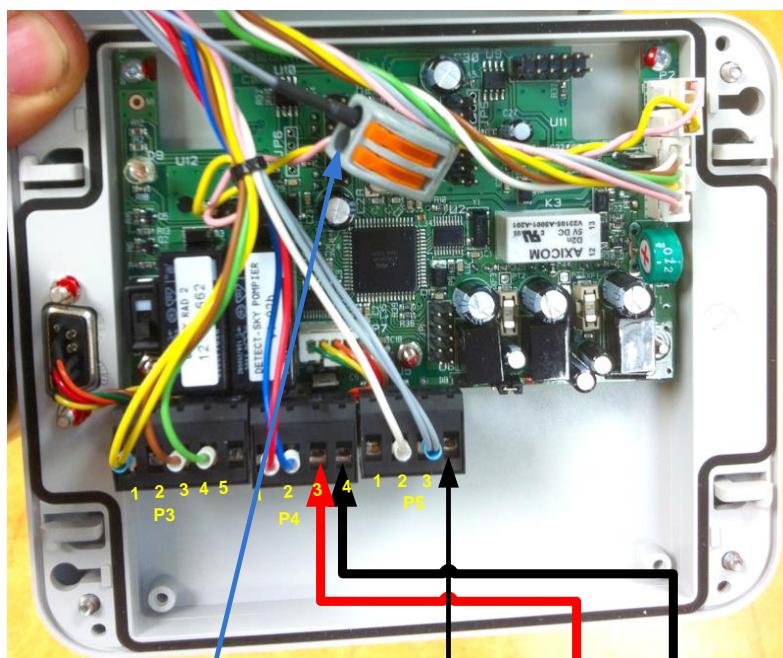
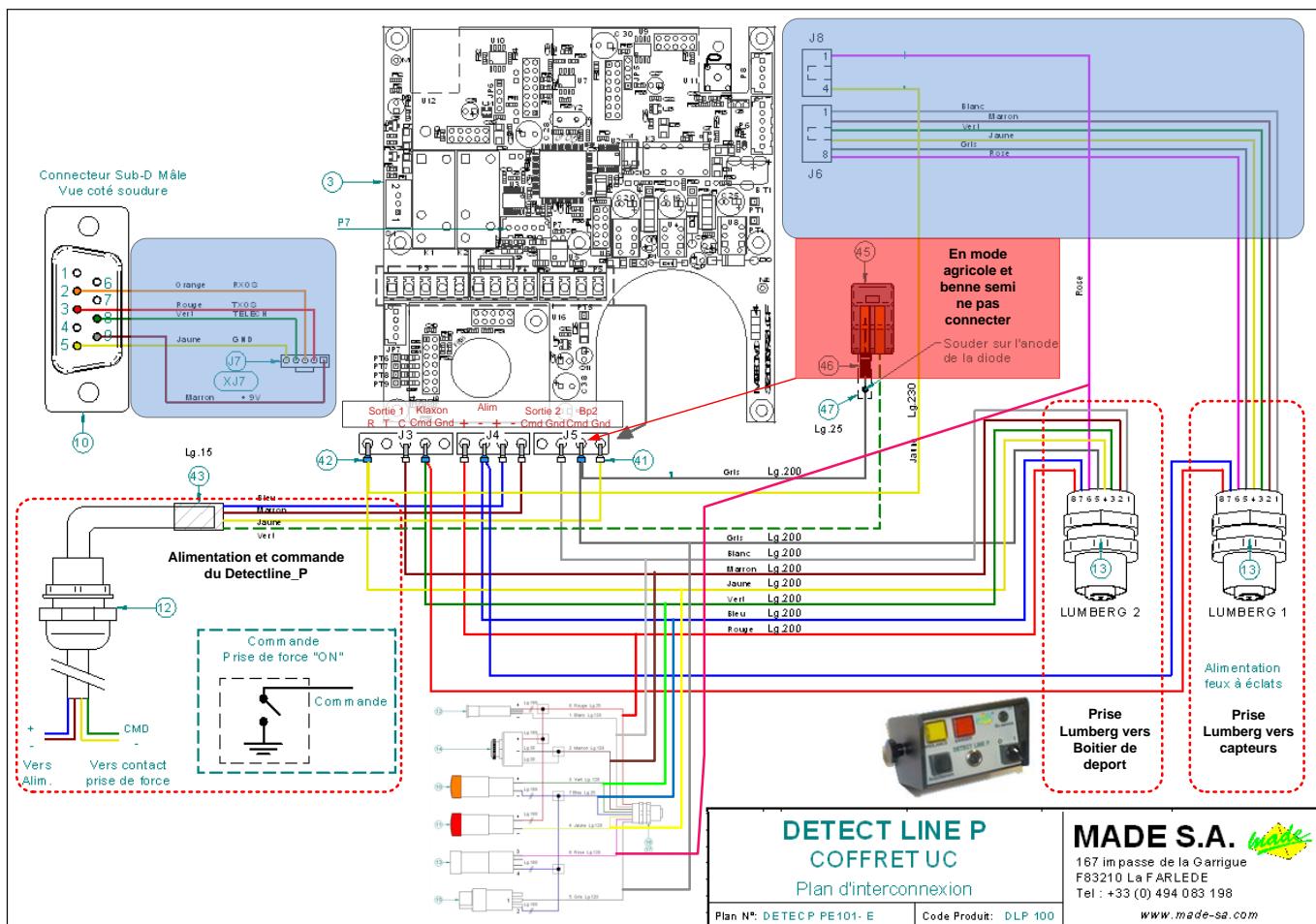
- Bring an externe 24V power supply to the pins 3-4 of the plug P4
- Connect an « activation to earth » command to Pin 3 of P5 (power take-off active and activation button)
- Plug in the connecting leads of the 2 sensors to the « Female Lumberg » connector
- Plug-in the lead from the remote box.

### 4.2 Layout Diagram

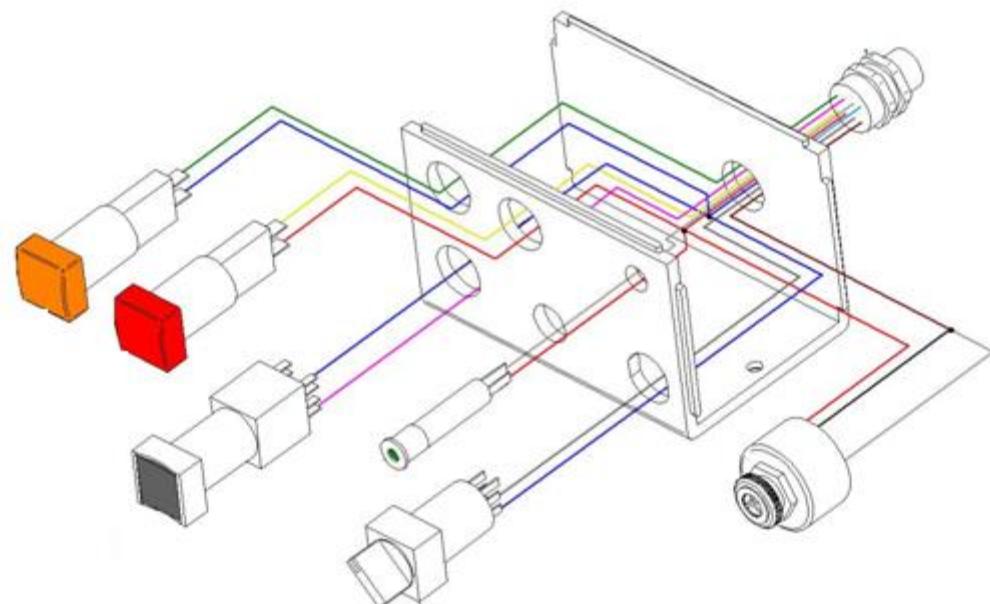
#### 4.2.1 Module Interconnections



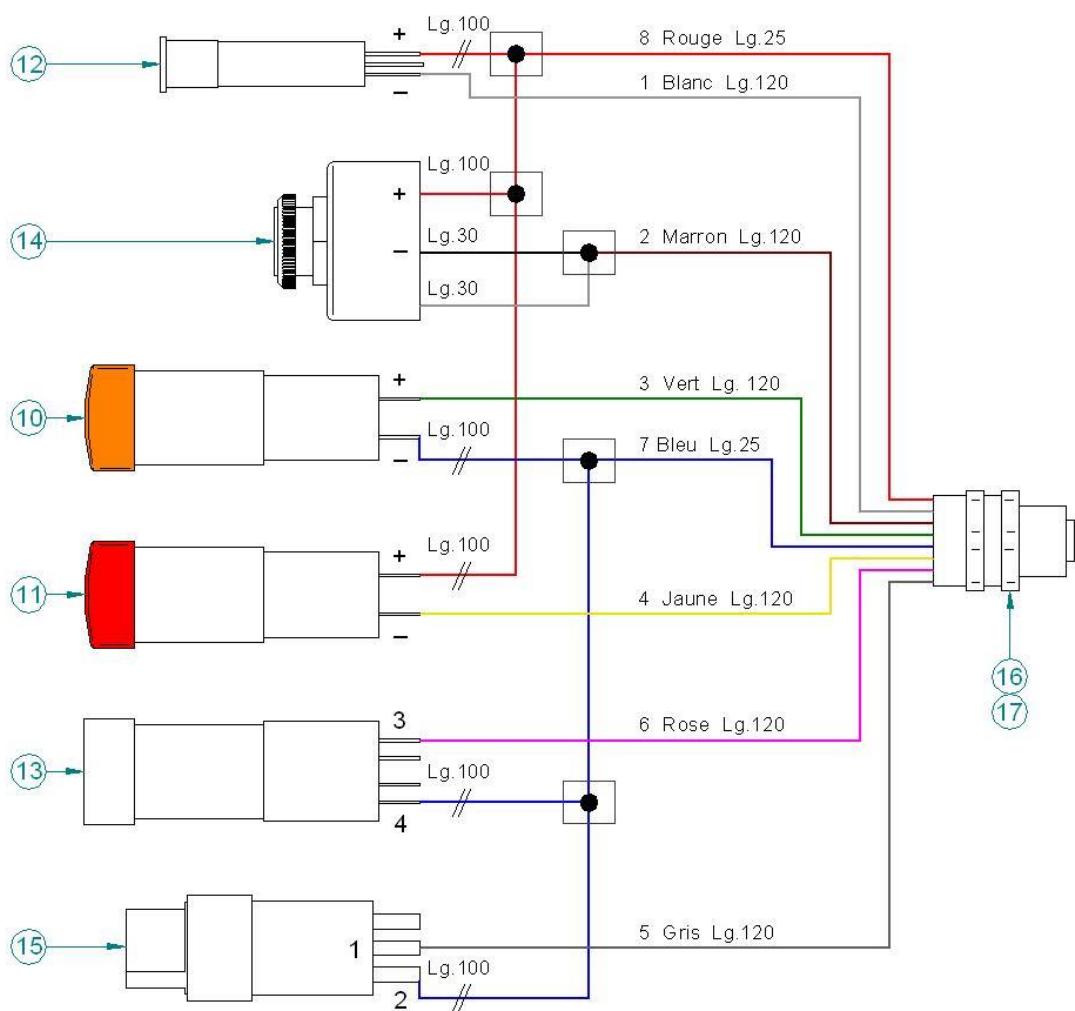
#### 4.2.2 Central Control Module electrical layout



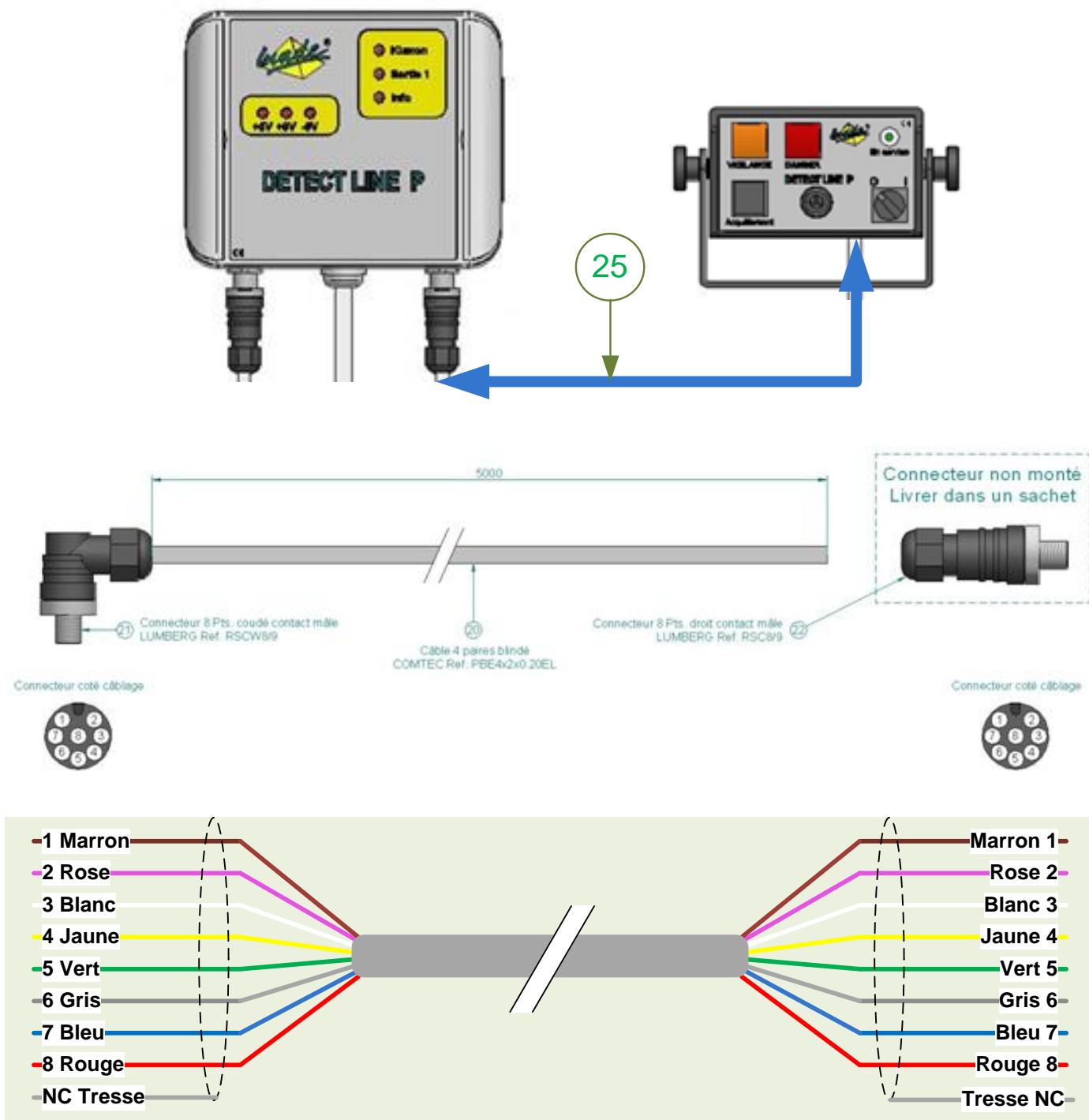
#### 4.2.3 Internal Cabling - remote box



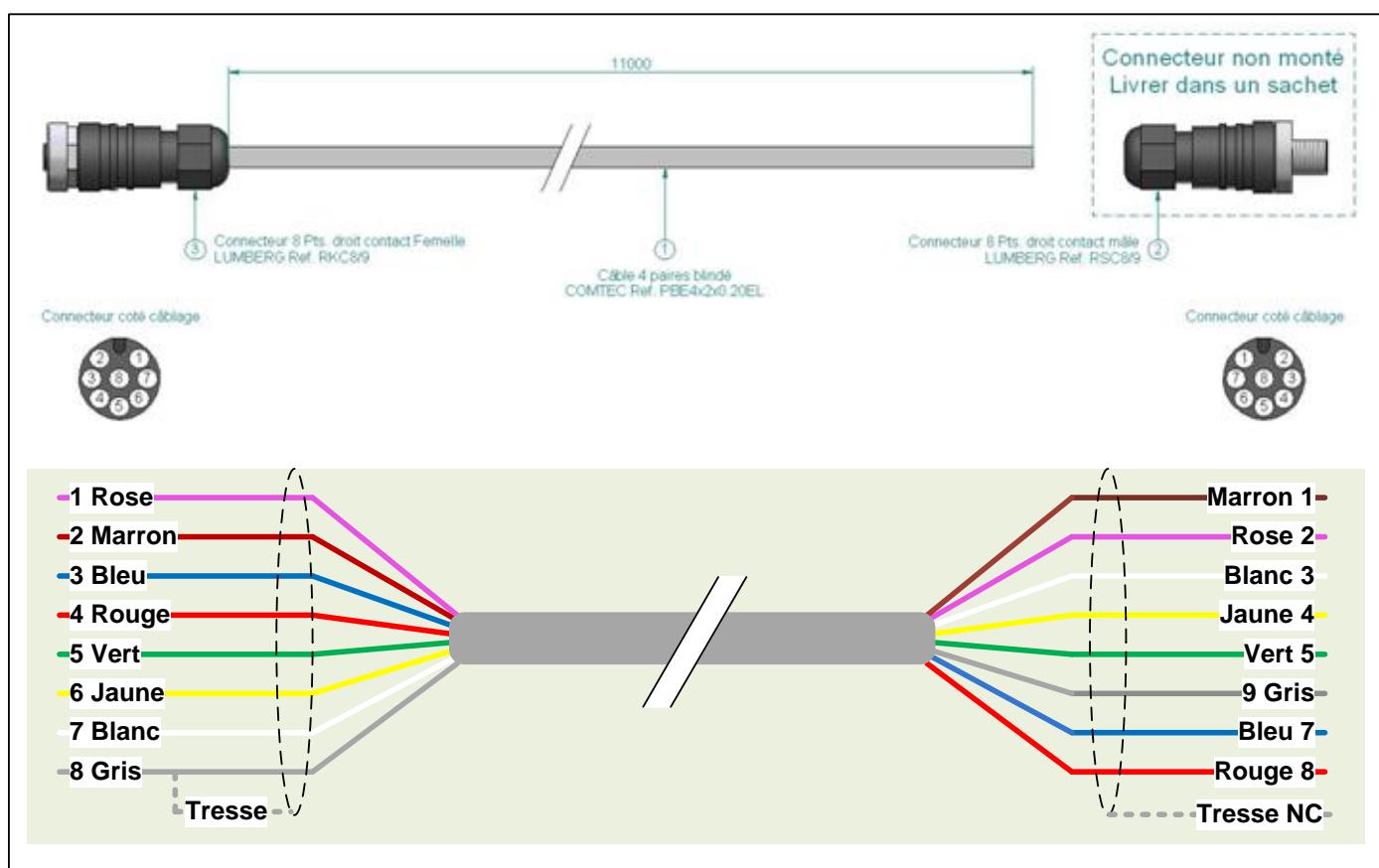
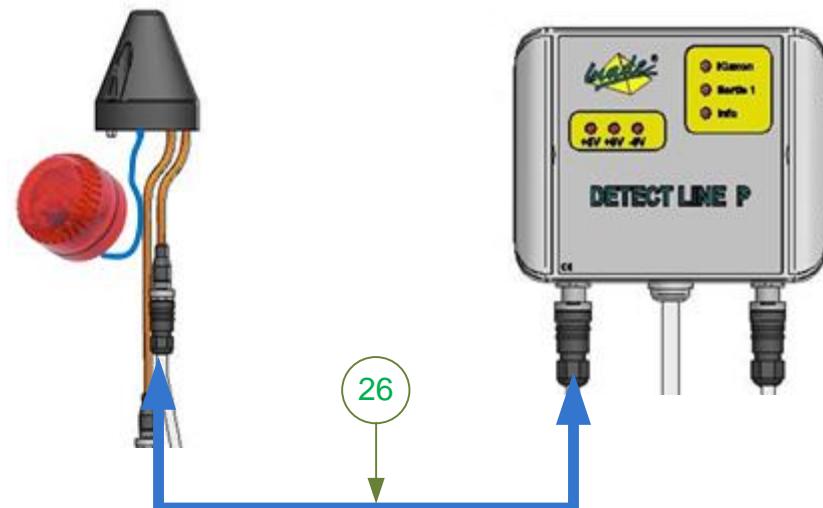
#### 4.2.4 Remote box electrical Layout



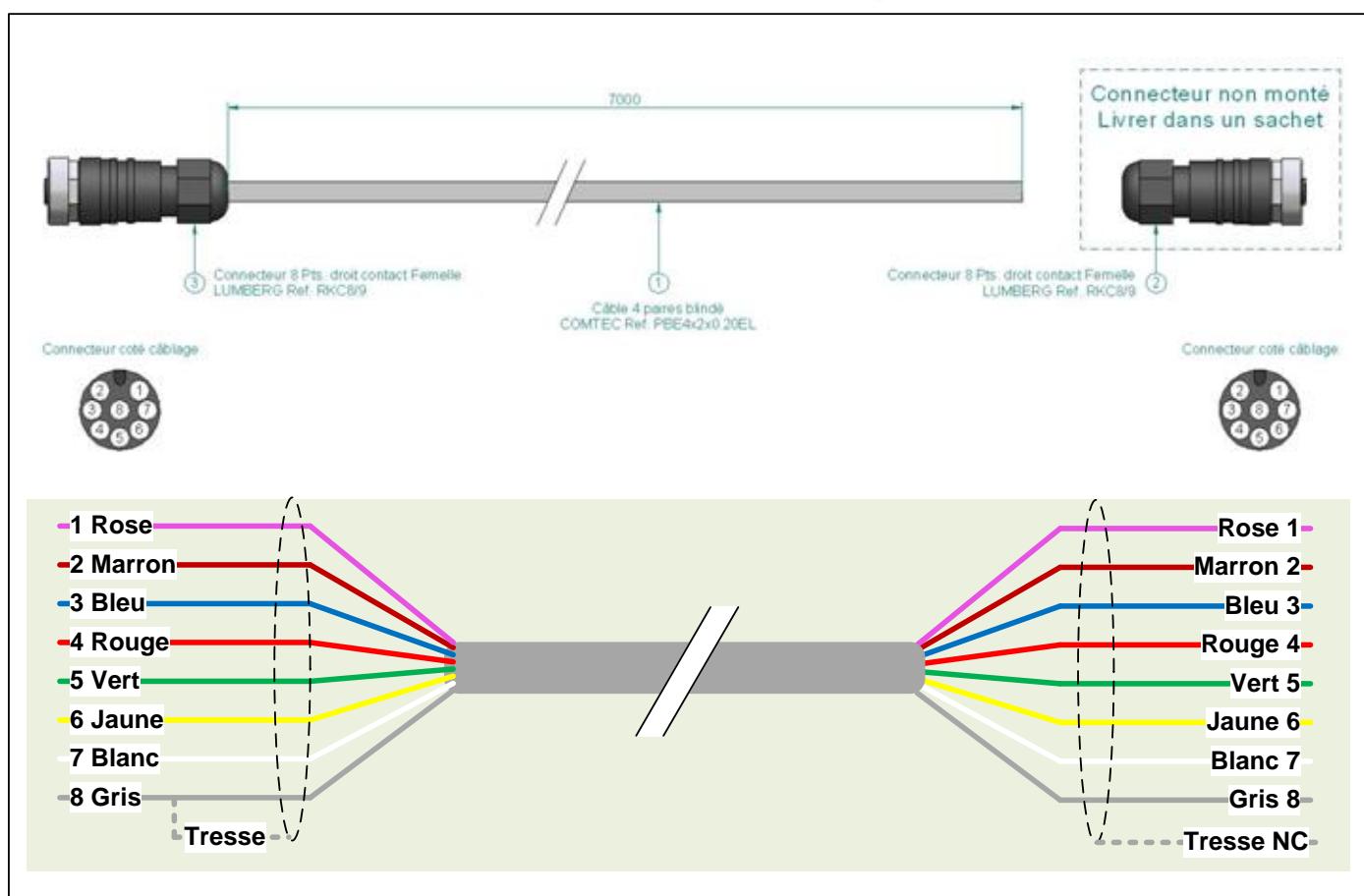
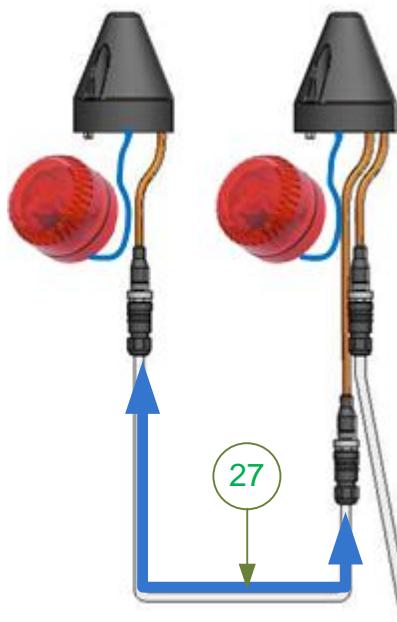
#### 4.2.5 Cable CCM to remote box



#### 4.2.6 Cable CCM to sensor

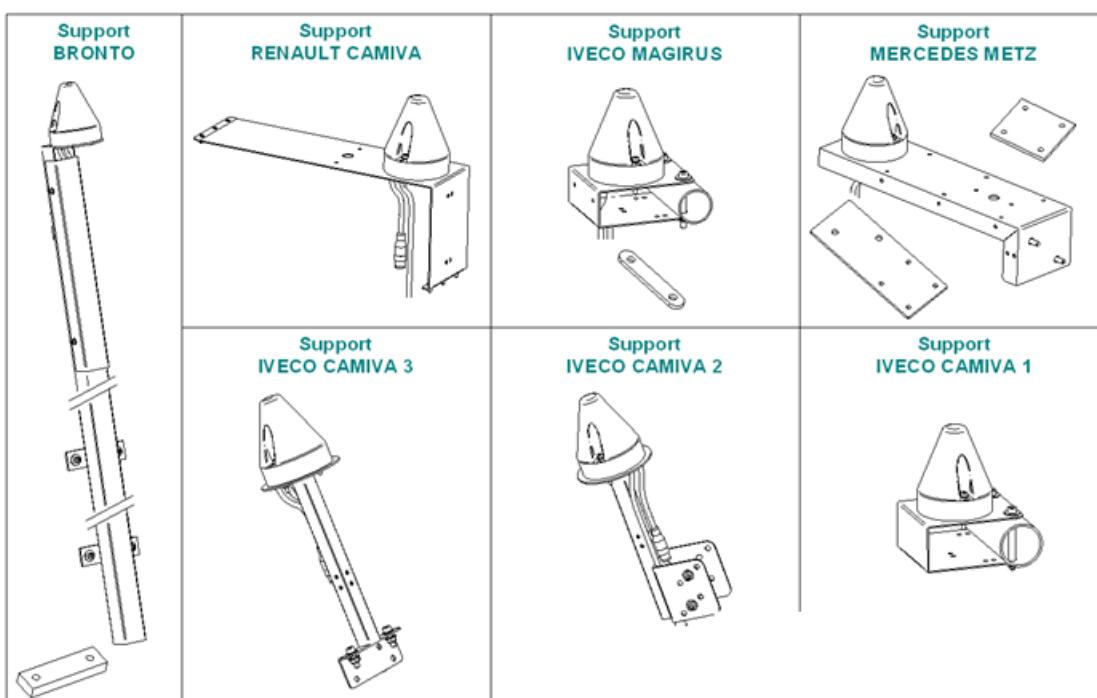
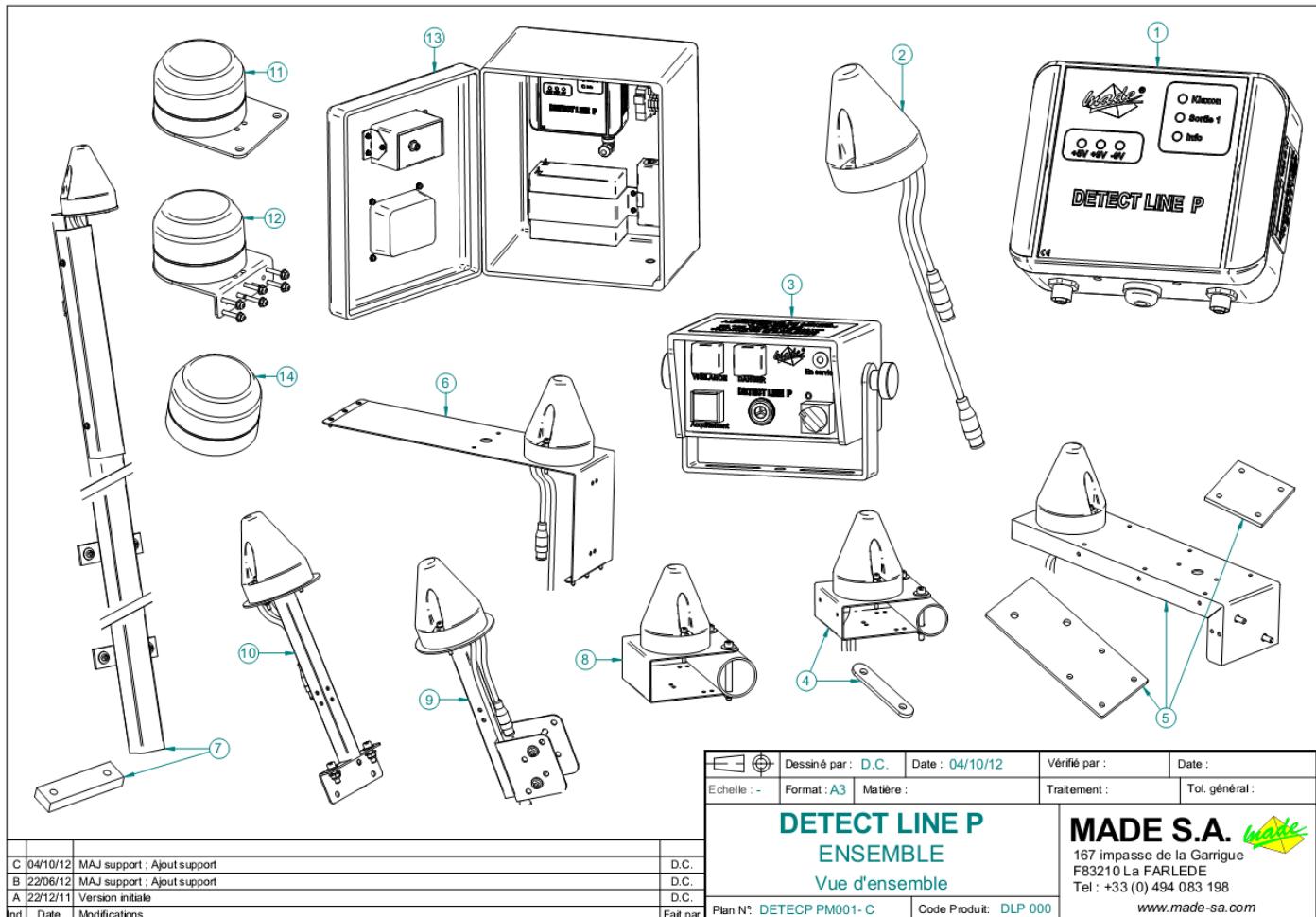


#### 4.2.7 Cable sensor to sensor



## 5 MODULE IDENTIFICATION

### 5.1 The various modules



## 5.2 Component List for the various modules

### COMPONENT LIST

<b>DETECT LINE P</b>	<b>Réf. : ENSEMBLE</b>	<b>Code produit : DLP 000</b>	<b>Date : 04/10/12</b>
<b>MADE S.A.</b> - 167 impasse de la Garrigue - 83 210 La FARLEDE		Référence document : DETECP PE001-C	
Repère	Désignation		
REP1	CCM Case		DLP 100
REP2	Sensor		DLP 200
REP3	Remote Box		DLP 300
REP 25	Cable CCM to remote Box		
REP 26	Cable CCM to sensor		
REP27	Cable sensor to sensor		
Options			
REP4	Sensor mounting IVECO MAGIRUS	DLP 410	
REP5	Sensor mounting MERCEDES METZ	DLP 420	
REP6	Sensor mounting RENAULT CAMIVA	DLP 430	
REP7	Sensor mounting BRONTO	DLP 440	
REP8	Sensor mounting IVECO CAMIVA 1	DLP 450	
REP9	Sensor mounting IVECO CAMIVA 2	DLP 460	
REP10	Sensor mounting IVECO CAMIVA 3	DLP 470	
REP11	Mounting Plate for the flashing light	DLP 510	
REP12	Support angle for the flashing light	DLP 520	
REP13	Transportable ladder	DLP 600	
REP14	Red flashing light	D93 H65 9-60Vcc	



RKC / RKCW 8-Pole



RSC / RSCW 8-Pole

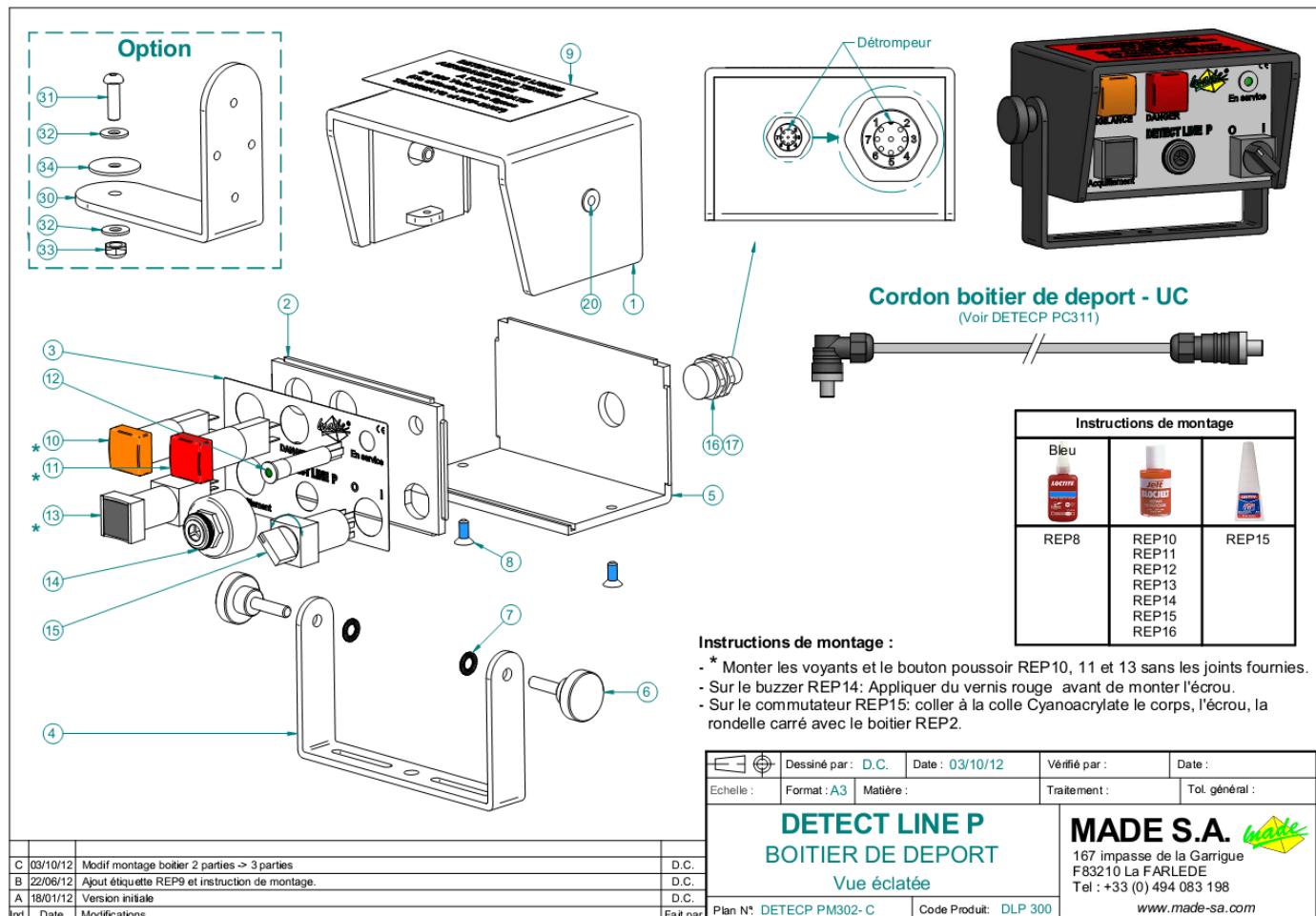


câble 8 conducteurs, multi  
brins, blindé, fil de masse  
0.22 blanc avec écran

## Spare Parts Schedule

Repère	Désignation
REP30	Connector Lumberg femal straight
REP31	Connector Lumberg femal elbowed
REP32	Connector Lumberg male straight
REP33	Connector Lumberg male elbowed
REP34	Cable 4*0.22 - 50m coil

## 5.3 Remote Box



## 5.4 Remote Box - List of materials

### PARTS L I S T

DETCT LINE P	Réf. : BOITIER DE DEPORT	Code produit : DLP 300	Date : 29/08/12
Repère	Désignation		
REP1	Box Upper part	DLP 301	
REP2	Box front face	DLP 302	
REP3	Front face polycarbonate	DLP 303	
REP4	Box support stirrup	DLP 304	
REP5	Box rear face	DLP 307	
REP6	Grooved Male Button	M5 D22 Lg.20	
REP7	Toothed Washer ExterChevauch. Stainless A2	AZ D5mm	
REP8	Stainless screw A2	TFHC M4x10	
REP9	Descriptive Label	DLP 306	
REP10	Square LED red	30V 15mA IP65	
REP11	Square LED yellow	30V 15mA IP65	
REP12	Round LED green	24V 20mA D9.5	
REP13	Square Push Button NO/NF black	250V 3A IP65	
REP14	Electronic Alarm mounting panel black	50/115dB D27	
REP15	2 position Selector square headed	250V 0.5A	
REP16	Panel base wire outlet 0.5m		
REP17	Screw for LUMBERG base	M12	
REP18	Heat Shrink sleeve black 2:1 (L1.2m)	D3.2 (Lg.mm)	
REP19	Heat Shrink sleeve black 2:1 (L1.2m)	D2.4 (Lg.mm)	
REP20 (Mounted by sub-contractor)	Tightening Srew, large head	M5 D10 Lg.13	
<b>Options</b>			
REP30	Angle Box support	DLP 305	
REP31	Stainless Screw inox A2	TCBHC M6x16	
REP32	Flat stainless washer A2	D6mm	
REP33	Hexagonal Stainless Nylon Locknut A2	NYLSTOP M6	
REP34	Flat, large stainless washer A2	LL Ø6mm	

## 5.5 Sensor Installation

The two sensors are fitted in an open space each side of the ladder



The ideal position is 20cm lower than the upper level of the large ladder.

## 5.6 Cabling of the sensor plugs

The plugs used have 8 contacts each, male and female. Ref. LUMBERG RSC 8/9 and LUMBERG RKC 8/9

See the cabling schemes chapters § 5.2.1 to ; § 5.2.5

Use type ACZ 2.\*75 screwdriver to tighten the connectors.  
Each wire can be crimped on a « Télémécanique » D0.25 connector element.

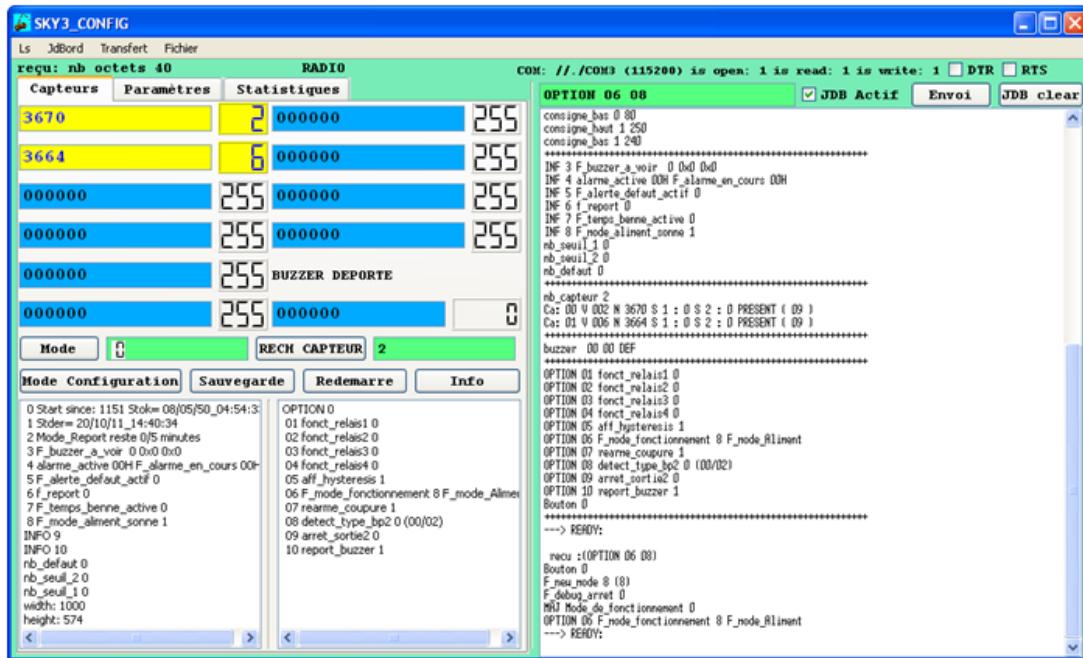


## 6 INITIALISATION and SETUP SOFTWARE

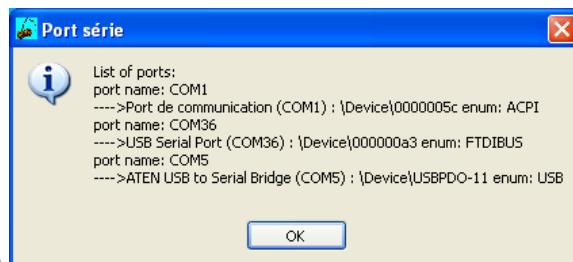
Remark : the Central control Module must be configured with the SKY3\_CONFIG.exe . software  
 This configuration software runs on a PC with: Win 98/2000/XP/SEVEN, with a séries connector (ex COM1). It is available on the site [www.made-sa.com](http://www.made-sa.com), with the link : <http://www.made-sa.com/expertise-reseaux/pompiers.htm> in **detect-line -> logiciel de configuration du DETECLINE-SKY NACELLE**

It installs automatically by executing the file « Detect\_SKy\_P\_instal.exe »

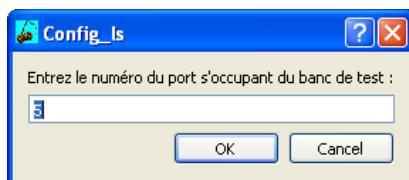
The connection cable is RS232 - female-female crossed.



First select the corresponding series port in the « Ls config » menu



A first screen indicates the series ports available



Next enter the number of the port

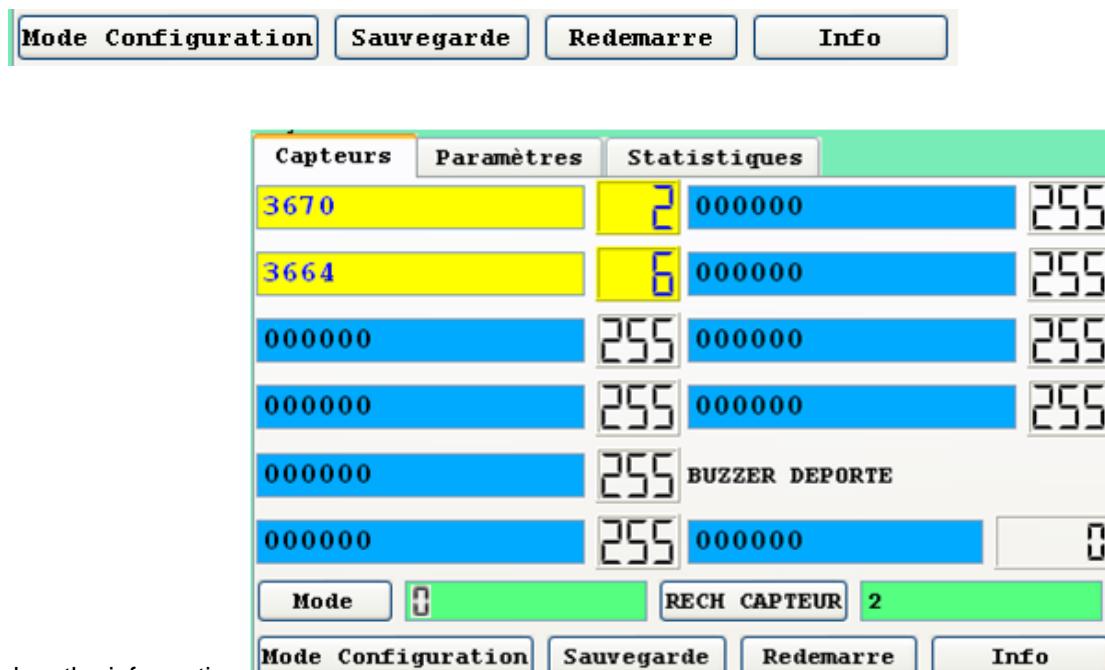
and validate the speed



the result is in the main window



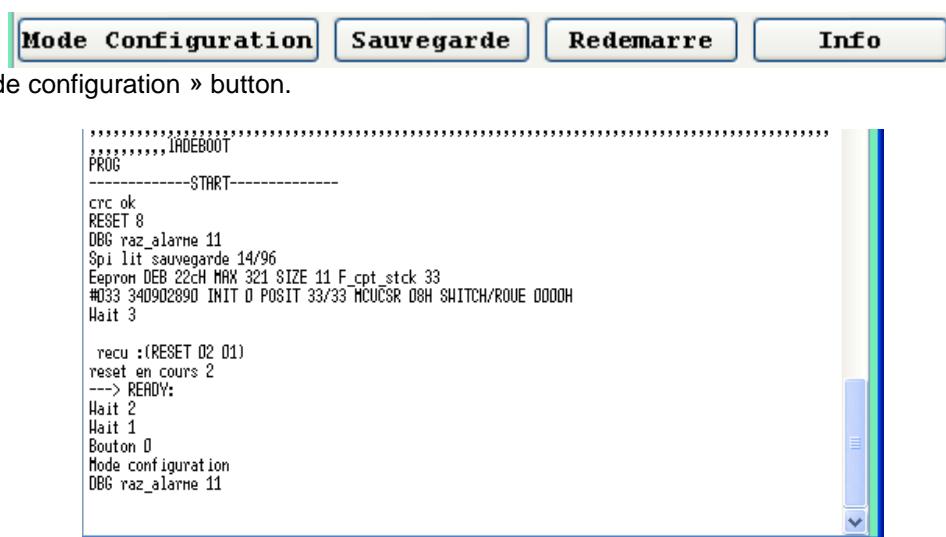
Once the series connection established, click on the « info » button.



The program refreshes the information

## 6.1 System Configuration

### 6.1.5 Changing to configuration mode



Specify the mode : Type « 1 » in the window and validate with the « MODE » button.

Reminder : the software is identical to that for the DETECTLINE POMPIER and the SKY NACELLE POMPIER. Only the choice of mode gives one or other type of function.

Mode 0 for DETECTLINE

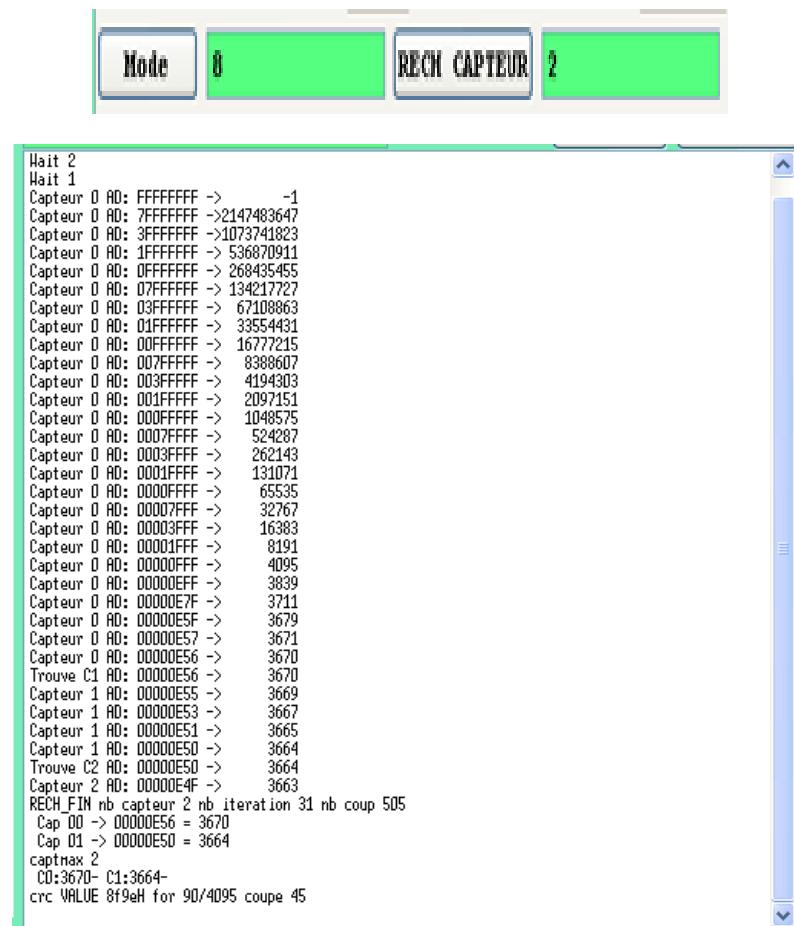
Mode 1 for the SKY NACELLE

Mode 2 for the SKY NACELLE type CAMIVA and SKY UC equipped with a tilt sensor.

Specify the number of the sensor : 2 (3 or 4) and validate with the « RECH CAPTEUR » button.

### 6.1.2 Locating the sensors

click on the « RECH CAPTEUR » button.



Once the sensors are located, click on the « info » button.



### 6.1.3 System backup

Click on the « Sauvegarde » button.



Once the report is completed, the system is operational.

### 6.1.4 Re-starting the system

Click on the « Redémarrer » button.



The system re-starts and the « info » led flashes.

A report is displayed with the following form :

NOTE : The « Paramètres » page gives access to the modification of the factory settings (detection thresholds, duration of the alarms, etc..) which are not normally changed.  
Any modification can only be carried out by a qualified person. Contact us.

**SKY3\_CONFIG**

Ls JdBord Transfert Fichier

**RADIO**

**Capteurs** **Paramètres** **Statistiques**

Seuil 1 (haut / bas)	Consigne	Seuil 2 (haut / bas)	
CONSIGNE 01 00	35	CONSIGNE 01 01	60
CONSIGNE 00 00	30	CONSIGNE 00 01	50

**TEMPS du SYSTEME**

T_100ms_rearme	300	T_100ms_arne	20
T_250ms_rbuzzer	120	T_250ms_abuzzer	8
T_100ms_seuil_1	32000	T_100ms_seuil_2	32000
T_im_max_report	15	T_is_max_benne	30
T_IS_max_Benne	8		

**interne s1 s2 defklaxon, haut**

TSEUIL 0	15	15	TSEUIL 1	10	10
TSEUIL 2	5	5	TSEUIL 3	2	10

**OPTION**

F_mode_fonctionnement	0				
fonct_relaiss1	0	fonct_relaiss2	0	fonct_relaiss3	0
fonct_relaiss4	0	aff_hysteresis	1	rearme_coupure	1
detect_type_bp	2	coupe_danger	0	coupe_alerte	0

Mise à jour DATE : 25/01/12 15:10:39

**Info** **EEPROM Save**

**COM: //./COM2 (115200) is open: i is read: i is write: i DTR RTS**

**INFO 01**  **JDB Actif** **Envoi** **JDB clear**

```

Spi écrit sauvegarde 14/96
INF 0 Start since: 0 Stok= 11/02/69_12:55:04
INF 1 Stder= 35/01/12_15:10:30
INF 2 Mode_Report resto 0/15 minutes
INIT H-S 0404H - 04F4H= 0080 spm 0404H sp 04CDH
-- Reste 038
-- Et0080 Freq 00 Ticks 25, Quant 25
INF 02 0244H-1000H= 0/00 spm 1000H sp 1000H
-- Reste 617
-- Et0080 Freq 10 Ticks 25, Quant 25
INF 03 0244H-00E4H= 0900 spm 0910H sp 0900H
-- Reste 865
-- Et0080 Freq 10 Ticks 25, Quant 25
Flg 03, SLP_Tim 0000 ch_val 0x00H
T2 0
Freat 0 P1: 0
Preat 0 1: 0
DBG_razz_alarme 2
#129 349283438 Ca: 00 V 000 N 3987 S 1 : 0 S 2 : 0 ABSENT ( 10 )
INF 3 F_buzzer_a_voix 0 0x0 0x0
INF 4 alarme_active 00H F_alarme_er_cours 00H
INF 5 F_alerte_defaut_actif 0
INF 6 f_report: 0
INF 7 f_temp_benne_active 0
INF 8 F_nb_seuil_val 0
nb_seuil_1 0
nb_seuil_2 0
DBG_defaut 2
DBG_razz_alarme 2
#129 349283438 Ca: 01 V 000 N 3987 S 1 : 0 S 2 : 0 ABSENT ( 10 )
INF 3 F_buzzer_a_voix 0 0x0 0x0
INF 4 alarme_active 00H F_alarme_er_cours 00H
INF 5 F_alerte_defaut_actif 0
INF 6 f_report: 0
INF 7 F_temp_benne_active 0
INF 8 F_nb_seuil_val 0
nb_seuil_1 0
nb_seuil_2 0
DBG_defaut 2
DBG_razz_alarme 1
#129 349283438 ALARME 0 VALIDE alarme_absent al_active 01H
DBG_ancl_defaut != etat_alerte.nb_seuil
DBG_Plante_capturé_absent
#129 349283438 DEMAR: (0) arret capteur indisponible
recu :(RADIO 00)
CMD? RADIO 00 (8)
---> READY:
recu :(INFO 01)
*****+
SKY_SP
1400
CALEND 00 25/01/12 15:10:39
Cap 00 -> 00000FC2 = 4034
Cap 01 -> 00000F95 = 3987
Cap 02 -> 00000F94 = C1:3987-
TEMPS 0 300 T 100ms_rearme

```

## 7 TEST

### 7.1 Procedure

Start the system.

Connect a computer to the CCM using the RD232 series connection; then open the SKY3\_config.exe. software  
Check the various points :

#### 7.1.1 Visual check

A visual inspection must be made of the sensors, the Central Control Module and the cabling.



The sensors are molded. They should not show shocks or splits.

The Central Control Module and the remote box in the cabin should not show shocks or splits.

The « info » lamp should flash regularly.  
The lamps +5V+9V-9V should be lit.

### 7.1.2 Verification by the Software

Connect a computer to the CCM using the RD232 series connection, open the SKY3\_config.exe. software. Once the software is started and the CCM recognised click on the « INFO » button.

Then it is enough to confirm that the sensors are recognised (red circle below)

The screenshot shows the SKY3\_CONFIG software interface. On the left, there's a table for 'Capteurs' (Sensors) with rows for 4034, 3987, 000000, 000000, 000000, BUZZER DEPORTE, and another 000000. A red circle highlights the first two rows. On the right, the 'INFO' tab is active, displaying sensor status and configuration. A red circle highlights the 'INFO' tab itself. Below the table, there's a 'Mode' dropdown set to 0, a 'RECH CAPTEUR' search bar containing '2', and several buttons: Mode Configuration, Sauvegarde, Redemarre, and Info. The 'Info' section contains a large amount of configuration text, with several lines circled in red, including 'Cat: 00 U 000 N 4034 S 1 : 0 S 2 : 0 ABSENT ( 10 )' and 'Cat: 01 U 000 N 3987 S 1 : 0 S 2 : 0 ABSENT ( 10 )'. At the bottom, there's a scrollable log area with more configuration details.

### 7.1.3 Sensor Verification

To check the sensitivity of the sensor, a simple method is to bring a 230V live mains lead close to the sensor.

The sensors are sufficiently sensitive to detect the field around this cable.



Check that the system is operating by causing each sensor to set off the alarm.

## 8 MAINTENANCE

Dismantling the components is forbidden. This operation is limited exclusively to personnel qualified by MADE.

An annual inspection can be carried out in our premises..

Use a dry cloth to clean the components.

Never use solvents or solvent-based products to for cleaning or maintenance.

## 9 MAINTENANCE

The system itself does not require re-calibration, Stricktly speaking there are no wearing parts.

Nevertheless,regular checks of the whole system enable verification of the operational function.

If the CCM or the sensors are changed, the « Configuration du système » procedure must be followed.

The maintenance procedure consists of running the test procedure.

### 9.1 Recommendations

In case of failure :

Check that the Central Control Module is running :

- Green lamps lit.

Check the sensors

Beneath the sensors, 2 leds indicate the function :

- One led lit continuously indicates the presence of sensor supply.
- The second led flashes to indicate the presence of dialogue with the CCM.

If the output one is lit, this indicates the presence of an electric field around one of the sensors.

From experience, 80% of failures come from the cabling between the CCM and the sensors.

## 10 OPERATIONAL RESTRICTIONS

The **DETECT LINE** system is *an operational aid*.

The operator must use maximum VIGILANCE and ATTENTION when near powered electric lines.

The principle applied is the measurement of the electric field radiated from the conductors.

**DETECT LINE** has been validated for utilisation in a FREE FIELD : with no physical obstacles between the sensor and the electric line.

**DETECT LINE** detects powered electric lines from 20000 volts.

Low voltage lines (380V) are not detected.

Certain cases (intersecting or parallel lines) can modify the strength of the electric field.  
In this case, greater care is necessary.

The **MADE** company declines all responsibility in the case of use of this system other than in conformance with the manufacturers instructions. The **MADE** company cannot be held responsible for an accident due to contact with electric lines, considering the multitude of specific cases met in the field.

## 11 RECYCLAGE

In accordance with the decree n° 2005-829 of July 20, 2005 relating to the waste disposal of electrical equipment and electronic (WEEE), the user ensures and takes responsibility for the collection and the elimination of the WEEE under the conditions of the articles 21 and 22 of this decree.

## 12 GUARANTEE

MADE guarantees this product, to the initial purchaser, against all material or functional failure during a period of one year from the date of delivery, unless otherwise indicated in the product manual. If a defect is discovered during the period of the guarantee, MADE agrees, at its choice, to either repair or replace the deficient part, excluding the expenses of handling and of initial delivery. All parts repaired or replaced under the terms of this agreement will be guaranteed only for the remainder of the period of initial guarantee of the system.

### 12.1 Limitations

This guarantee does not cover:

- Damage caused by a "cause beyond control", natural disasters, strikes, wars (declared or not), terrorism, social conflicts or any acts under governmental jurisdiction
- Damage due to misuse, to carelessness, to any accident or an unsuitable application or installation
- Damage caused by a repair or an attempted repair not authorized by MADE
- Any product that is not used in accordance with the instructions provided by MADE
- Cost of transport back to MADE
- Cost of transport by express delivery of parts or products under guarantee
- Cost travel for a repair on site under guarantee

This guarantee constitutes the unique explicit guarantee established by MADE for its products. All implied guarantees, including, but not limited to, guarantees on the commercial value of the product and its suitability for a particular use are positively rejected.

The present guarantee confers certain rights : the legislation of the country or jurisdiction can grant others. This guarantee constitutes the final declaration, complete and exclusive, of the terms of the guarantee and no body is allowed to give other guarantees or promises on MADE's account.

### 12.2 Claims Limitations

Claims having for object repair or replacement are the only allowable claims in case of the breaking of this guarantee. The MADE Company cannot be held responsible, whether on the basis of strict responsibility or any other legal basis, of any incidental or consecutive damage resulting from a violation of the guarantee or from carelessness.

## 13 COPYRIGHT

© All rights reserved. The distribution and the copying of this document, as well as the use and the communication of its content, are forbidden without written authorization of MADE.

The content of this document is destined for use only as information. It can be modified without prior notice and must not be considered as an obligation by MADE.

MADE declines all responsibility for mistakes or inaccuracies that the present document may contain.

## 14 APPENDIX

## 14.1 Declaration of Conformity CE



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## Déclaration CE de conformité

Déclaration n : **CE\_DLP\_01/2013**

Le fabricant soussigné :

MADE SA

167, Impasse de la Garrigue  
F 83210 LA FARLEDE

Déclare que le produit

Nom du produit : **Détecteur de lignes à hautes tensions HTA, HTB**  
Référence du modèle : **DETECLINE P**

Est conforme aux dispositions réglementaires définies par :

Les directives européennes :

- CEM 2004/108/CE relative au « Marquage CE »
- 2006/95/CE relative à la sécurité des matériels électriques destinés à être employés dans certaines limites de tension.
- Directive 2004/104/CE relative aux sous-ensembles électroniques (ESAs) et les équipements électroniques de seconde monte dans les véhicules à moteur et leurs remorques.

Suite aux essais effectués par le laboratoire, EMITECH (Ref rapport d'essai: R041-12-105298-1), l'équipement référencé ci-dessus est conforme à la Directive 2004/104/CE.

Par ailleurs, le produit désigné ci-dessus a été conçu, fabriqué et contrôlé, dans le cadre d'un Système d'Assurance Qualité certifié conforme à la norme : ISO 9001/2008, par l'Association Française pour l'Assurance Qualité – AFAQ, certificat : QUAL / 2005 / 24473B du : 05 / 05 / 2011.

Fait à La Farlède, le 11 janvier 2013

Directeur Général	Directeur Technique	Responsable Qualité
Erick Papillon 	Philippe Picon 	Jean Yves Creste 

## 14.2 Déclaration de conformité CEM automobile



**M A D E**  
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## Déclaration de CE conformité CEM Automobile

Déclaration n : CE\_DLP\_03/2013

### CEM Automobile

Le fabricant soussigné :

MADE SA

167, Impasse de la Garrigue  
F 83210 LA FARLEDE



Déclare que le produit

Nom du produit : **Détecteur de lignes à hautes tensions HTA, HTB**

Référence du modèle : **DETECLINE P**

Est conforme aux dispositions réglementaires définies par :

Les directives européennes :

- CEM 2004/108/CE relative au « Marquage CE»
- 2006/95/CE relative à la sécurité des matériels électriques destinés à être employés dans certaines limites de tension.
- Directive 2004/104/CE relative aux sous-ensembles électroniques (ESAs) et les équipements électroniques de seconde monte dans les véhicules à moteur et leurs remorques.
  - o Emission rayonnée électrique - CISPR 25
  - Immunité conduite aux impulsions - ISO 7637-2
  - Mesures temporelles - ISO 7637-2

Suite aux essais effectués par le laboratoire, EMITECH (Ref rapport d'essai: R041-12-105298-1), l'équipement référencé ci-dessus est conforme à la Directive 2004/104/CE.

Par ailleurs, le produit désigné ci-dessus a été conçu, fabriqué et contrôlé, dans le cadre d'un Système d'Assurance Qualité certifié conforme à la norme : ISO 9001/2008, par l'Association Française pour l'Assurance Qualité – AFAQ, certificat : QUAL / 2005 / 24473B du : 05 / 05 / 2011.

Fait à La Farlède, le 22 janvier 2013

Directeur Général	Directeur Technique	Responsable Qualité
Erick Papillon, 	Philippe Picon 	Jean Yves Creste 

R.C. TOULON 381 537 604 (91 800 341) – SIRET 381 537 604 (00021) – CODE NAF 6202A  
N° TVA Intra communautaire FR 20 3815 37604

## 14.3FS\_detectline\_pompier\_V\_1\_02



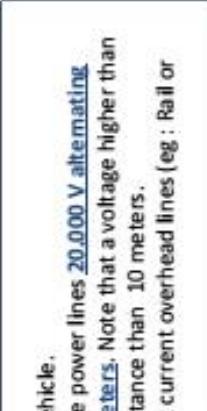
## DETECT LINE POMPIER (Detection of overhead high Voltage lines &gt; 20 000V)

**1. Overview:**

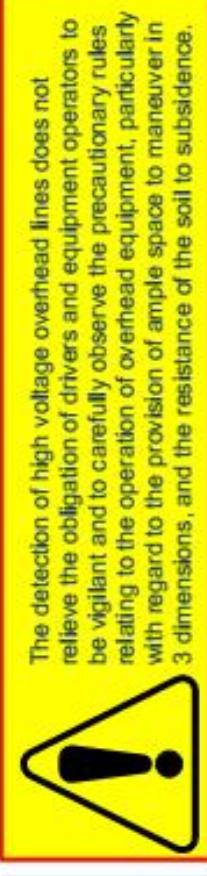
This system is installed permanently on the vehicle.

It is calibrated to detect overhead high voltage power lines **20 000 V alternating current**, at a distance of approximately **40 meters**. Note that a voltage higher than 20 000 V will set off a warning at a greater distance than 10 meters.

**Important :** The system does not detect direct current overhead lines (eg : Rail or Tramway Catenary's)

**2. System elements :**

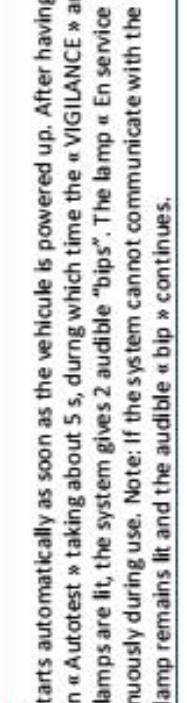
- 1 Central Control Module (placed behind the seat of the nacelle operator )
- 1 Remote Control Box (placed close to the nacelle operator's position )
- 2 Sensors (placed on each side of the cab roof)



The detection of high voltage overhead lines does not relieve the obligation of drivers and equipment operators to be vigilant and to carefully observe the precautionary rules relating to the operation of overhead equipment, particularly with regard to the provision of ample space to maneuver in 3 dimensions, and the resistance of the soil to subsidence.

**3. Start-up :**

The system starts automatically as soon as the vehicle is powered up. After having carried out an « Autotest » taking about 5 s, during which time the « VIGILANCE » and « DANGER » lamps are lit, the system gives 2 audible “bips”. The lamp « En service » flashes continuously during use. Note: If the system cannot communicate with the sensors, the lamp remains lit and the audible « bip » continues.

**4. Operation :**

At the approach to the 40 m zone around a 20 000 V line, the yellow « VIGILANCE » lamp lights. If the « vigilance » zone is penetrated, the red lamp lights in turn and flashes, and the audible alarm begins.

**5. In transit :**

The system is ready to operate but the audible and visual alarms are off. The use as desired by the equipment operator of the switch 6 (manual negotiation) enables the activation / negation of the alarm in transit mode.

**6. During intervention :**

whatever the position of the switch (6), the audible alarm sounds in the "danger" zone according to the mode chosen at installation, as soon as the parking brake or the power take-off are activated. Push-Button « Acquisition » (5) : Pressing this button stops the audible alarm (with a reminder each 30 seconds). The alarm is reactivated if the parking brake lever or the power take-off command are moved.

**7. Maintenance :**

The system requires no specific maintenance. Nevertheless, it is up to the users to report all failures or anomalies that are observed.

**1: Audible Alarm Buzzer**

2 Lamp « En service » ( flashing when all is OK, continuous if there is a problem of communication with the sensors )

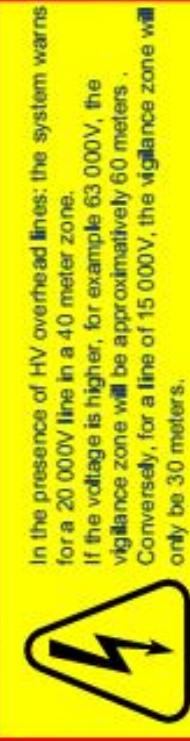
**3 Lamp « VIGILANCE »****4 Lamp « DANGER »**

5 Button « Acquisition » for the audible alarm alone

6 Switches for activating the alarm manually.

In the presence of HV overhead lines, the system warns for a 20 000 V line in a 40 meter zone. If the voltage is higher, for example 63 000V, the vigilance zone will be approximately 60 meters . Conversely, for a line of 15 000V, the vigilance zone will only be 30 meters.

The detection of a power line does not stop the movement of the high-lift equipment, but merely informs the operator(s) of the presence of the HV line



## 14.4 Fiche produit DETECT\_LINE POMPIER



DéTECTeur  
de lignes  
Haute  
Tension  
pour moyens  
aériens



## L'EXPERTISE DES RESEAUX

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# DETECT LINE POMPIER

## DETECTEUR DE LIGNES HAUTE TENSION

DETECT LINE a été développé en 2002 pour répondre à un besoin des bétonniers.

Huit ans après, la famille de détecteurs de lignes hautes tensions développée par MADE est expressément recommandée par le syndicat du béton et équipe 80% des pompes à bétons.

Toujours à l'écoute de ses partenaires, MADE a adapté ses systèmes de détection aux pompiers.



### APPLICATION

DETECT LINE est un dispositif de détection de champ électrique des lignes Haute Tension : HTA ( $\geq 20000$  V) et HTB ( $\geq 50000$  V) en champ libre.

DETECT LINE est une aide à la conduite permettant d'identifier la proximité d'une zone à risques , à une distance configurable jusqu'à 40 m d'une ligne HTA selon le type de véhicule.



### PRESENTATION

DETECT LINE est composé de deux capteurs positionnés de chaque côté du parc. Les capteurs sont reliés par un câble à l'unité centrale (UC) placée dans la cabine et communiquent en permanence avec cette dernière. Un boîtier de dépôt permet de reporter les informations sur le tableau de bord du camion, devant le chef d'agrès.



### FONCTIONNEMENT

DETECT LINE mesure le champ électrique environnant d'une ligne HTA ( $\geq 20000$  V ) et HTB ( $\geq 50000$  V).

Lorsque l'engin arrive sur une zone d'intervention, l'utilisateur active le DETECT LINE via un interrupteur. Si le véhicule pénètre dans une zone à risque (distance de 40m d'une ligne HTA), une alarme sonore et un voyant lumineux se déclenchent. L'enclenchement de la prise de force active le système automatiquement au cas où le chef d'agrès ne l'aurait pas mis en service manuellement. Au final, avant que les occupants quittent la cabine pour intervention, ils auront eu au préalable l'information de la présence ou non d'une ligne Haute Tension dans la zone d'évolution de leurs moyens aériens.



### CARACTERISTIQUES TECHNIQUES

	Boîtier de traitement UC	Capteur moulé
Alimentation	12V / 24V sur l'alimentation du véhicule	Via UC, par connexion étanche et fil blindé
Dimension	160 x 130 x 60 mm	70 x 120 mm
Température d'utilisation		-20° C + 60° C
Etanchéité		IP 65
Précision de la mesure		± 4 m en dynamique, pour une vitesse d'engin de 1 m/s
Seuils de détection		20 m à 40 m d'une ligne HTA

# DETECT LINE - SKY NACELLE

## DETECTEUR DE LIGNES HAUTE TENSION



Normalisation :Respect des normes NF EN 50082-1 : CEM et NF EN 61010-1 :

Sécurité électrique. Nos détecteurs de lignes à haute tension aériennes bénéficiant de marquage CE.

La société MADE ne pourra être tenue responsable de quelques dommages qu'ils soient, directs ou indirects, et rappelle que les systèmes sont des moyens de préventions qui ne soustraient pas l'utilisateur à la réglementation en vigueur, telle que définie dans les articles 172 et 173 du décret du 8 janvier 1965 et modifiés par décret du 6 mai 1995.

Afin d'améliorer ses produits la société MADE se réserve le droit de modifier, à tout moment et sans aucun préavis, les produits décrits dans cette documentation.

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FP\_DETECT\_LINE\_POMPIER\_V\_3\_00\_FR\_FEV2012

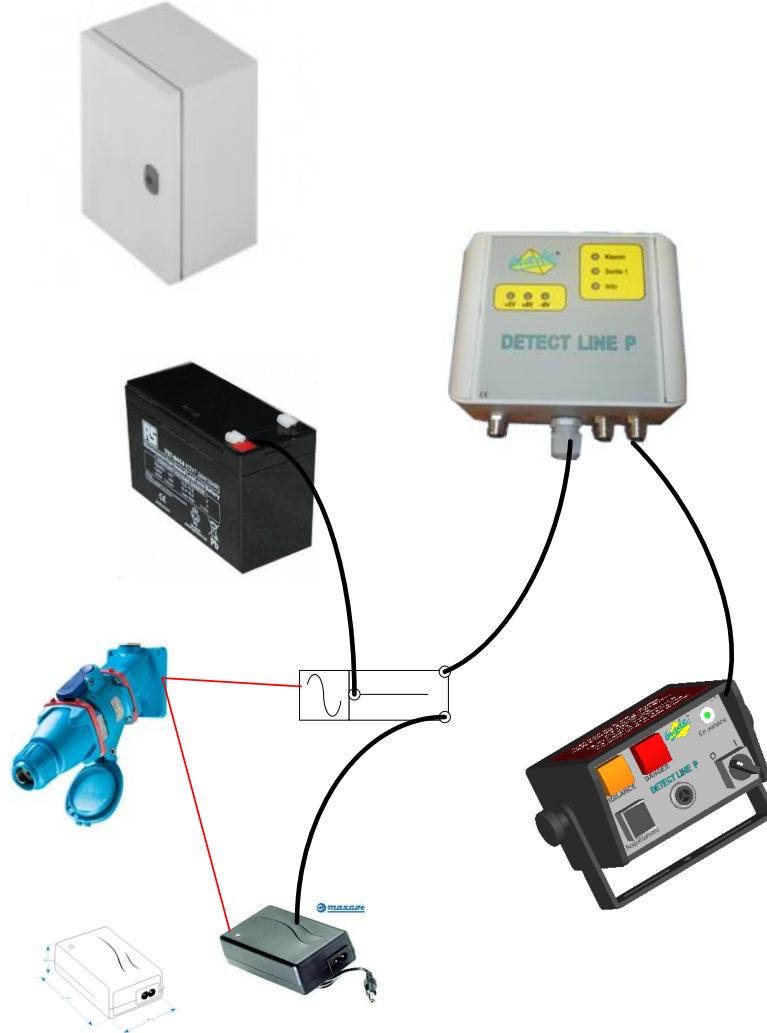


## 14.5 Self-contained system for independant ladders

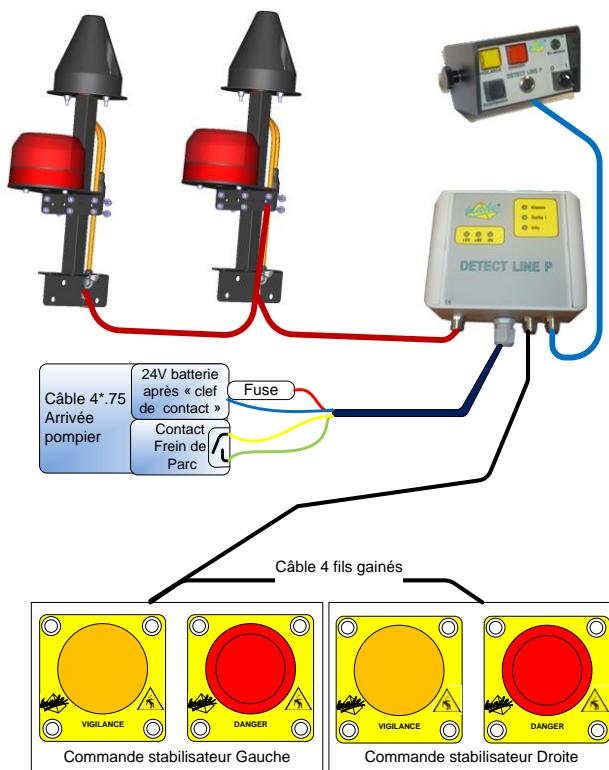
This single-case system is offered for transportable ladders, so as to render the system autonomous for any intervention and to automatically manage the battery charge during storage.



### 14.5.5 Interconnexion of the modules in the case



## 14.6 Optional remote Lamp on the stabilisation controllers



The CCM is ready to receive the cable. It is equipped with a wago 2pts connector, the lamps are mounted with the label, on the chassis at the rear



Connecteur UC	Fil	Voyant zone 1	Fil	Voyant Zone 2
Wago 2 pts blue	Blue	Yellow 1	Blue	Yellow 1
Wago 2 pts Green	Green	Yellow 2	Green	Yellow 2
Wago 2 pts Red	Brown	Red 1	Brown	Red 1
Wago 2 pts Yellow	Yellow	Red 2	Yellow	Red 2

